

Hitting Meets Packing: How Hard Can It Be?

Jacob Focke¹ Fabian Frei¹ Shaohua Li¹ Dániel Marx¹
Philipp Schepper¹ Roohani Sharma² Karol Węgrzycki^{3,4}

¹ CISPA | ² University of Bergen

³ MPI Informatics, SIC | ⁴ Saarland University

ESA 2024 – September 2, 2024



A Set of Unrelated Problems

Triangle Partition

Vertex Cover

Minimum s - t -cut

Maximum Matching

Feedback Vertex Set

Cycle Cover

Odd Cycle Transversal



A Set of Unrelated Problems

*Partition the graph
into triangles*

Triangle Partition

*Select vertices
to cover all edges*

Vertex Cover

Minimum s - t -cut *Separate two vertices by the
optimal vertex removals*

*Select the maximum number
of disjoint edges*

Maximum Matching

Feedback Vertex Set *Remove vertices to make
the graph a forest*

Cycle Cover

*Cover (all) vertices
using only cycles*

Odd Cycle Transversal

*Delete vertices to make
the graph bipartite*



A Set of Unrelated Problems

*Partition the graph
into triangles*

Triangle Partition

*Select vertices
to cover all edges*

Vertex Cover

Odd Cycle Packing

Minimum s - t -cut

*Separate two vertices by the
optimal vertex removals*

*Select the maximum number
of disjoint edges*

Maximum Matching

Chordal Deletion

Tree Cover

Feedback Vertex Set

*Remove vertices to make
the graph a forest*

Clique Covering Number

H -Hitting

Cycle Cover

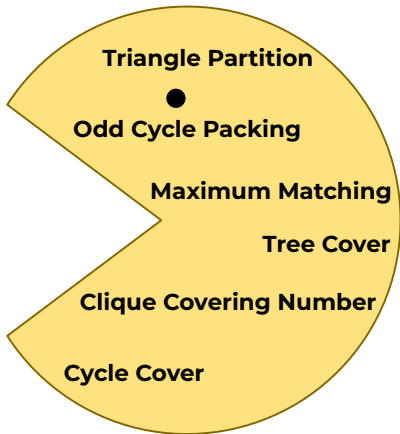
*Cover (all) vertices
using only cycles*

Odd Cycle Transversal

*Delete vertices to make
the graph bipartite*



A Set of Unrelated Problems



Packing Problems

Vertex Cover

Minimum s - t -cut

Chordal Deletion

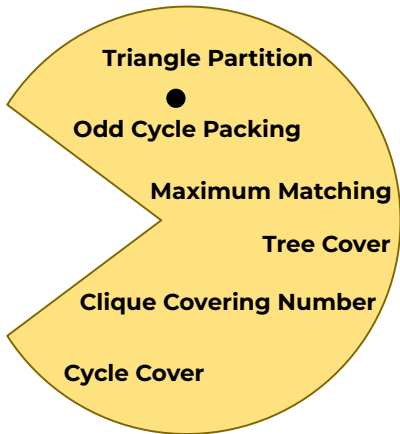
Feedback Vertex Set

H -Hitting

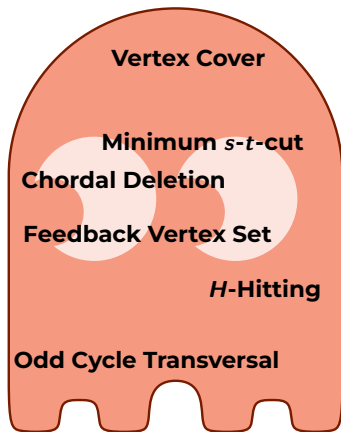
Odd Cycle Transversal



A Set of Unrelated Problems



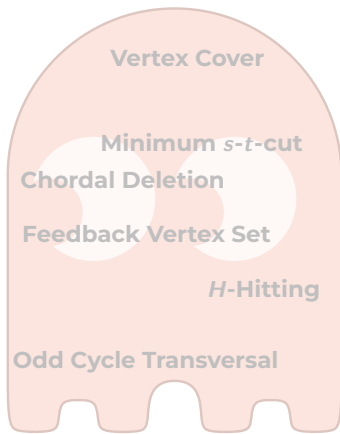
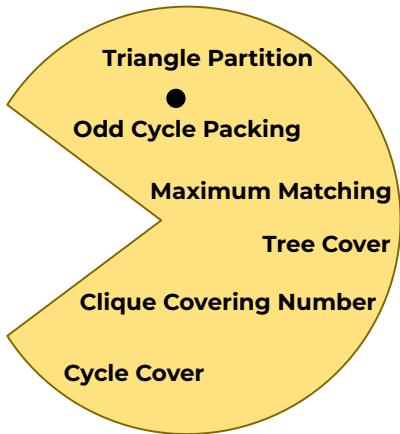
Packing Problems



Hitting Problems



Packing Problems



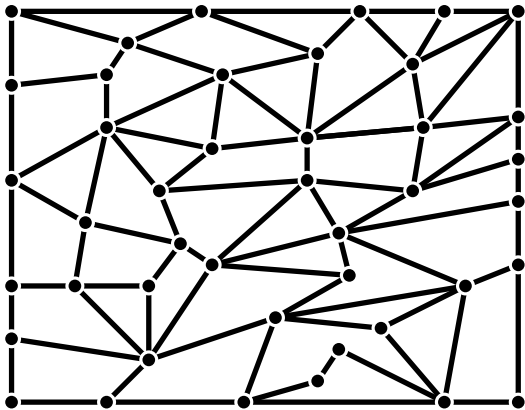


Packing Problems

H -PACKING for a fixed graph H

Input: A graph G , an integer ℓ .

Task: Pack ℓ copies of H in a vertex-disjoint way in G .





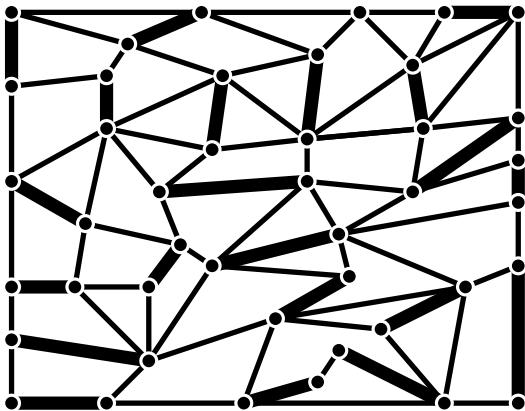
Packing Problems

H -PACKING for a fixed graph H

Input: A graph G , an integer ℓ .

Task: Pack ℓ copies of H in a vertex-disjoint way in G .

- Maximum Matching:
 $H = K_2 \rightsquigarrow$ “Edge Packing”





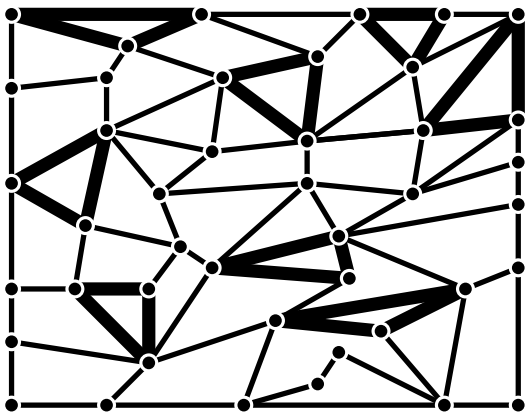
Packing Problems

H -PACKING for a fixed graph H

Input: A graph G , an integer ℓ .

Task: Pack ℓ copies of H in a vertex-disjoint way in G .

- Maximum Matching:
 $H = K_2 \rightsquigarrow$ “Edge Packing”
- Triangle Covering:
 $H = C_3 \rightsquigarrow$ “Triangle Packing”





Packing Problems

H -PACKING for a fixed graph H

Input: A graph G , an integer ℓ .

Task: Pack ℓ copies of H in a vertex-disjoint way in G .

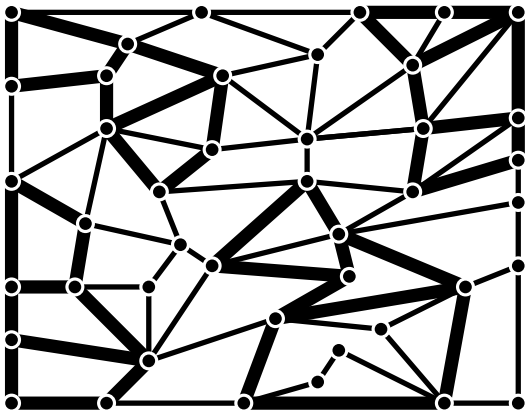
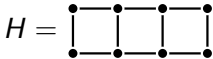
- Maximum Matching:

$H = K_2 \rightsquigarrow$ “Edge Packing”

- Triangle Covering:

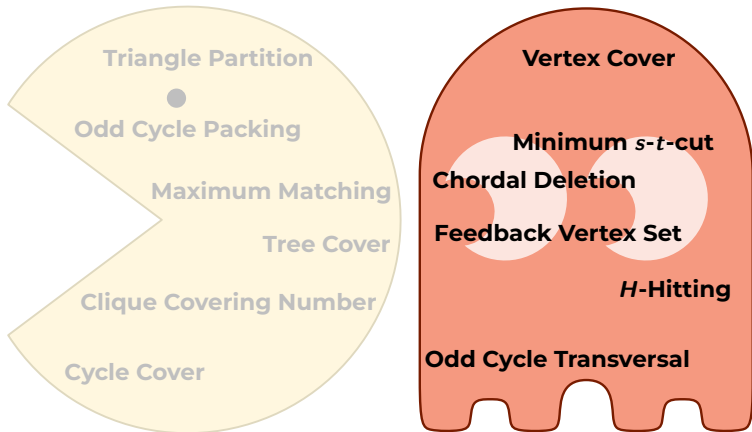
$H = C_3 \rightsquigarrow$ “Triangle Packing”

- H -PACKING where





Hitting Problems



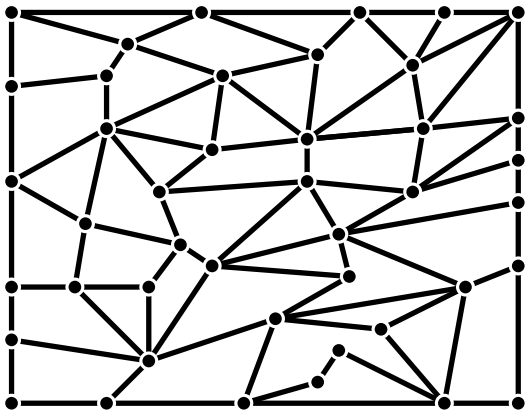


Hitting Problems

H -HITTING for a fixed graph H

Input: A graph G , an integer k .

Task: Delete k vertices such that no copy of H remains in G .





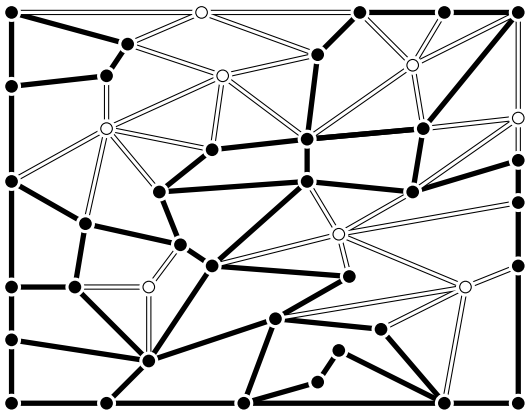
Hitting Problems

H -HITTING for a fixed graph H

Input: A graph G , an integer k .

Task: Delete k vertices such that no copy of H remains in G .

- Triangle Hitting:
 $H = C_3 =$ a triangle





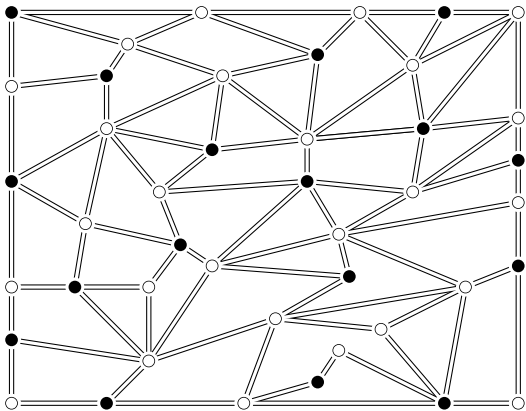
Hitting Problems

H -HITTING for a fixed graph H

Input: A graph G , an integer k .

Task: Delete k vertices such that no copy of H remains in G .

- Triangle Hitting:
 $H = C_3 =$ a triangle
- Vertex Cover:
 $H = K_2 \rightsquigarrow$ “Edge Hitting”



Deleted Vertices = Vertex Cover!



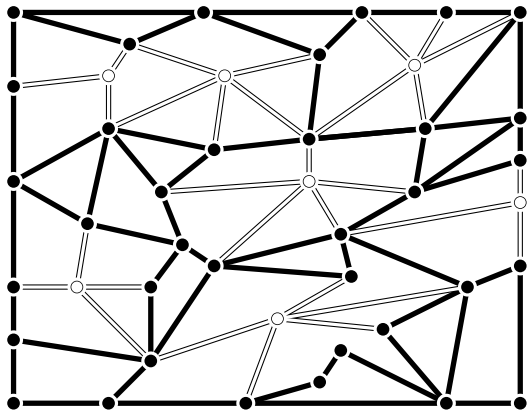
Hitting Problems

H -HITTING for a fixed graph H

Input: A graph G , an integer k .

Task: Delete k vertices such that no copy of H remains in G .

- Triangle Hitting:
 $H = C_3 =$ a triangle
- Vertex Cover:
 $H = K_2 \rightsquigarrow$ "Edge Hitting"
- H -HITTING where
 $H =$






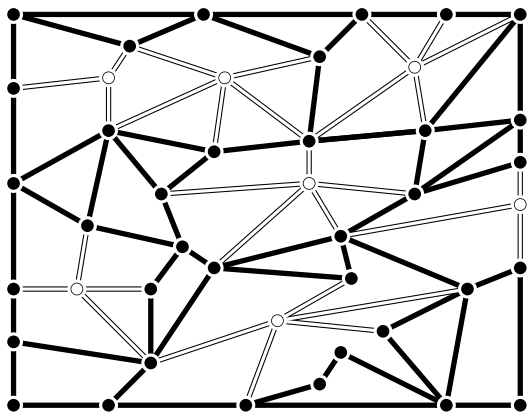
Hitting Problems

H -HITTING for a fixed graph H

Input: A graph G , an integer k .

Task: Delete k vertices such that no copy of H remains in G .

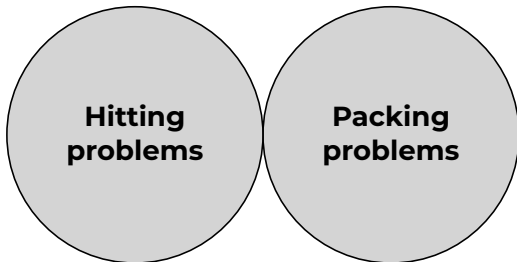
- Triangle Hitting:
 $H = C_3 =$ a triangle
- Vertex Cover:
 $H = K_2 \rightsquigarrow$ "Edge Hitting"
- H -HITTING where
 $H =$ 



also known as covering or transversal

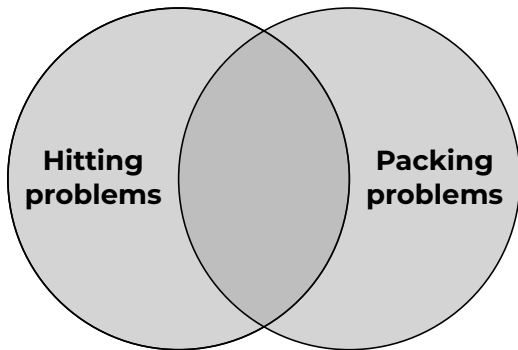


Hitting Meets Packing



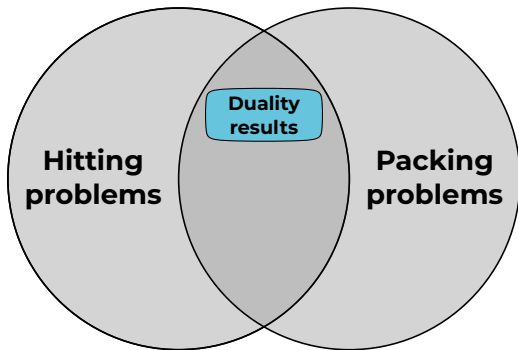


Hitting Meets Packing





Hitting Meets Packing

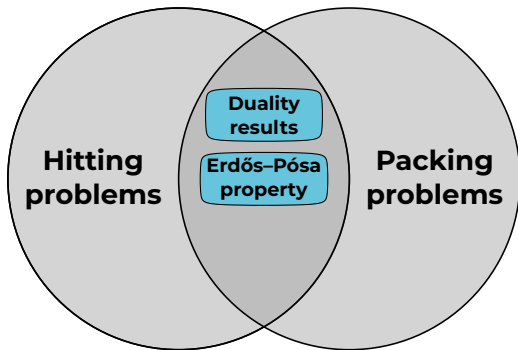


Duality Results:

If we destroy all copies of H by deleting k vertices, then we can pack at most k copies of H .



Hitting Meets Packing

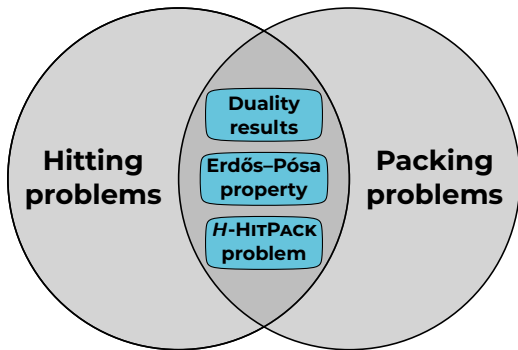


Erdős-Pósa property:

If we can pack ℓ cycles,
then we can hit all cycles by removing $k = \mathcal{O}(\ell \log \ell)$ vertices.



Hitting Meets Packing



***H*-HITPACK:**

A generalization of Hitting and Packing that makes both problems “more robust” (\rightsquigarrow notion of stability).

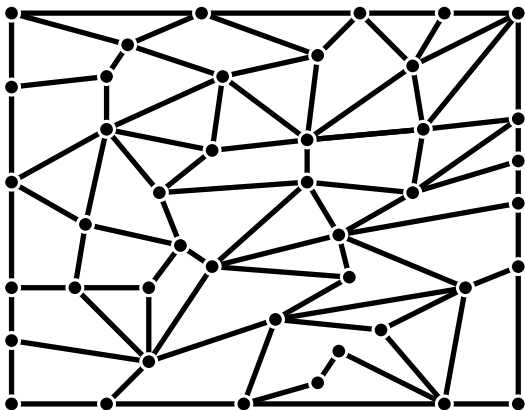
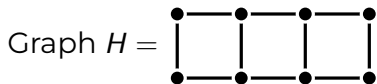


H-HITPACK for a fixed graph H

Input: A graph G , integers k and ℓ .

Task:

Delete k vertices such that we cannot pack $\ell + 1$ copies of H .





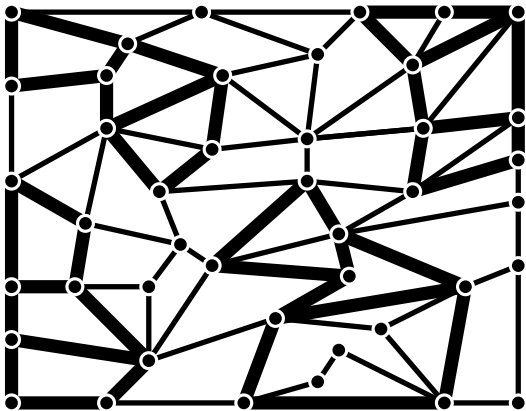
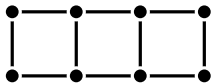
H-HITPACK for a fixed graph H

Input: A graph G , integers k and ℓ .

Task:

Delete k vertices such that we cannot pack $\ell + 1$ copies of H .

Graph $H =$



H -PACKING

$(k = 0, \ell = 4)$

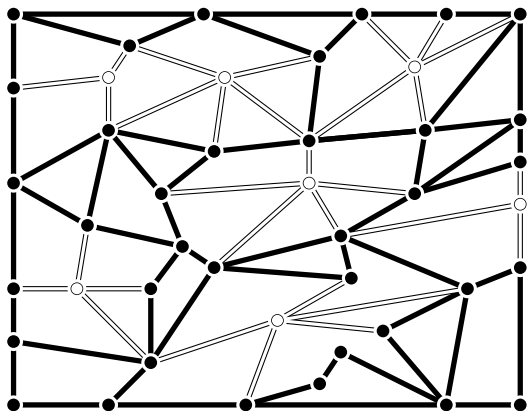
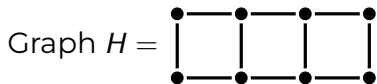


H-HITPACK for a fixed graph H

Input: A graph G , integers k and ℓ .

Task:

Delete k vertices such that we cannot pack $\ell + 1$ copies of H .



H -HITTING

$(k = 7, \ell = 0)$

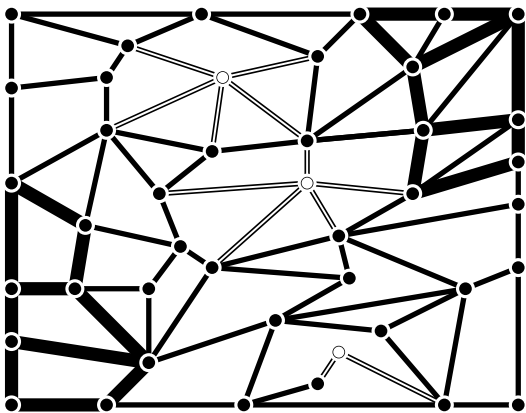
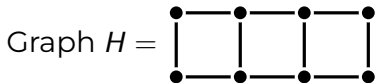


H-HITPACK for a fixed graph H

Input: A graph G , integers k and ℓ .

Task:

Delete k vertices such that we cannot pack $\ell + 1$ copies of H .



H -HITPACK

$(k = 3, \ell = 2)$



Our Contribution

Fix a connected graph H :

Theorem (Algorithmic Results)

H -HITPACK can be solved in time $2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}} \cdot |G|^{\mathcal{O}(1)}$.



Our Contribution

Fix a connected graph H :

Theorem (Algorithmic Results)

H -HITPACK can be solved in time $2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}} \cdot |G|^{\mathcal{O}(1)}$.

Theorem (Hardness Results)

H -HITPACK is complete for $\Sigma_2^P = \text{NP}^{\text{NP}} = \text{NP}^{\text{coNP}}$.

No $2^{2^{o(\text{tw})}} \cdot |G|^{\mathcal{O}(1)}$ -time algorithm unless ETH fails.



Our Contribution

Fix a connected graph H :

Theorem (Algorithmic Results)

H -HITPACK can be solved in time $2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}} \cdot |G|^{\mathcal{O}(1)}$.

Theorem (Hardness Results)

H -HITPACK is complete for $\Sigma_2^P = \text{NP}^{\text{NP}} = \text{NP}^{\text{coNP}}$.

No $2^{2^{o(\text{tw})}} \cdot |G|^{\mathcal{O}(1)}$ -time algorithm unless ETH fails.

Summary: The problem is *double*-exponential in treewidth!

Although the base problems are much simpler.



The Source of Hardness

H*-HITPACK for a fixed graph *H

Input: A graph G , integers k and ℓ .

Task:

Delete k vertices such that we cannot pack $\ell + 1$ copies of H .



The Source of Hardness

H -HITPACK for a fixed graph H

Input: A graph G , integers k and ℓ .

Task:

Is there a set S of at most k vertices such that every H -packing in $G - S$ contains at most ℓ copies of H .



The Source of Hardness

H -HITPACK for a fixed graph H

Input: A graph G , integers k and ℓ .

Task:

Is there a set S of at most k vertices such that every H -packing in $G - S$ contains at most ℓ copies of H .

Once we “guessed” the set S , we need to argue about *all possible* H -packings for the remaining graph!



The Source of Hardness

H*-HITPACK for a fixed graph *H

Input: A graph G , integers k and ℓ .

Task:

Is there a set S of at most k vertices such that every H -packing in $G - S$ contains at most ℓ copies of H .

\rightsquigarrow \exists

\rightsquigarrow \forall

Once we “guessed” the set S , we need to argue about *all possible* H -packings for the remaining graph!

Hints at the Σ_2^P -hardness \leftarrow



The Source of Hardness

H*-HITPACK for a fixed graph *H

Input: A graph G , integers k and ℓ .

Task:

Is there a set S of at most k vertices
such that every H -packing in $G - S$
contains at most ℓ copies of H .

\rightsquigarrow \exists

\rightsquigarrow \forall

Once we “guessed” the set S , we need to argue
about *all possible* H -packings for the remaining graph!

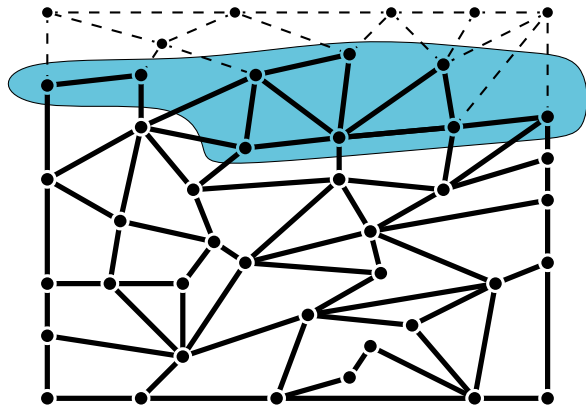
Hints at the Σ_2^P -hardness

Main Question: How does this affect the algorithm?



Algorithmic Idea

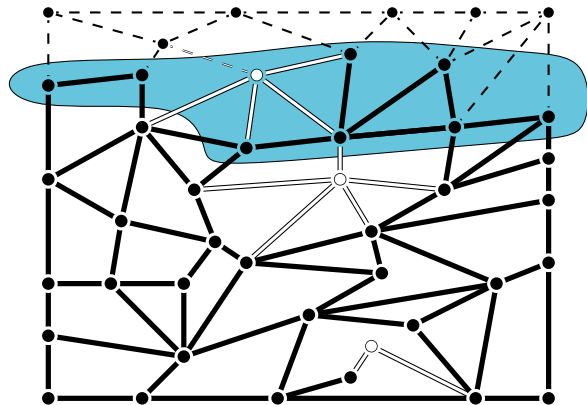
Fix a bag of the decomposition (i.e., a separator):





Algorithmic Idea

Fix a bag of the decomposition (i.e., a separator):

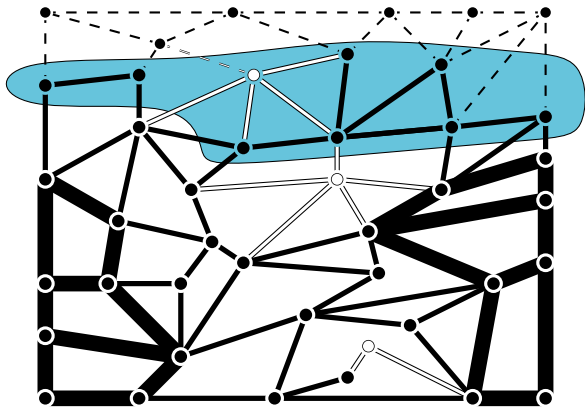


1 Guess the deleted vertices.



Algorithmic Idea

Fix a bag of the decomposition (i.e., a separator):

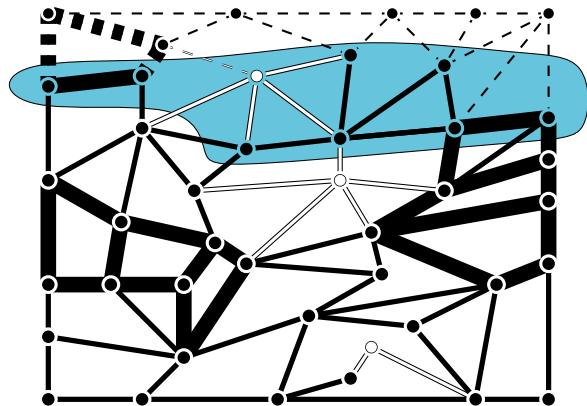


- 1 Guess the deleted vertices.
- 2 For each partial H -packing, store the size of the packing.



Algorithmic Idea

Fix a bag of the decomposition (i.e., a separator):

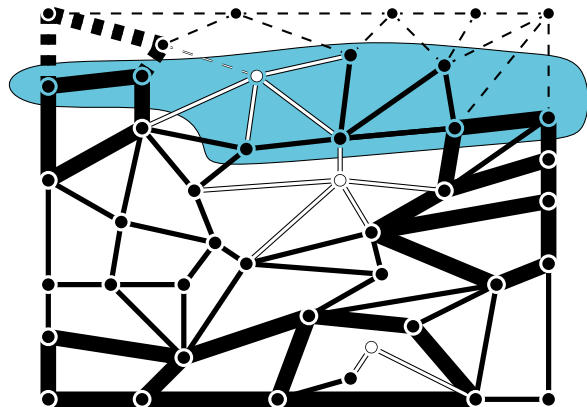


- 1 Guess the deleted vertices.
- 2 For each partial H -packing, store the size of the packing.



Algorithmic Idea

Fix a bag of the decomposition (i.e., a separator):

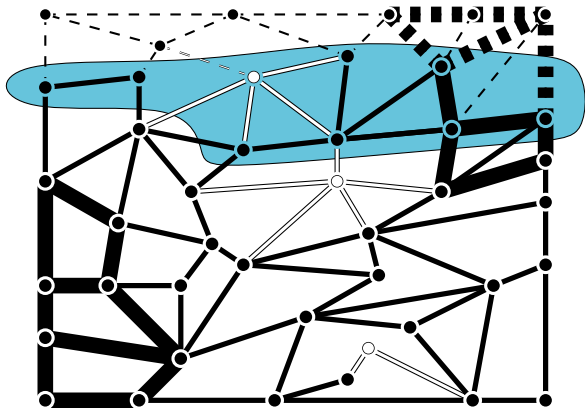


- 1 Guess the deleted vertices.
- 2 For each partial H -packing, store the size of the packing.



Algorithmic Idea

Fix a bag of the decomposition (i.e., a separator):

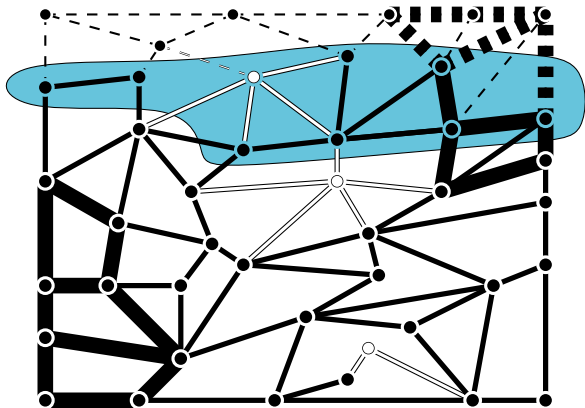


- 1 Guess the deleted vertices.
- 2 For each partial H -packing, store the size of the packing.



Algorithmic Idea

Fix a bag of the decomposition (i.e., a separator):

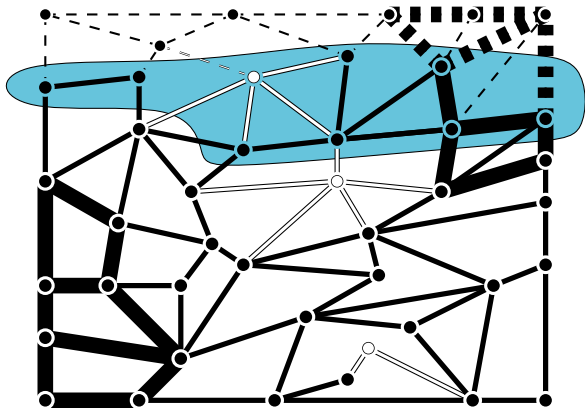


- 1 Guess the deleted vertices.
- 2 For each partial H -packing, store the size of the packing.
- 3 If there is a packing with $> \ell$ copies of H , then discard the current guess.



Algorithmic Idea

Fix a bag of the decomposition (i.e., a separator):

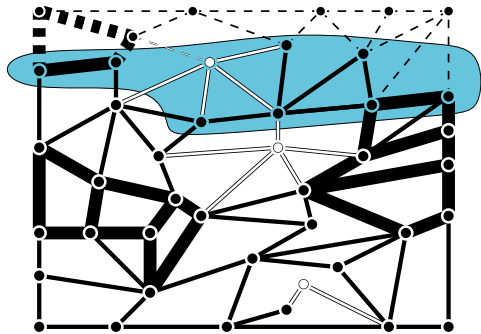
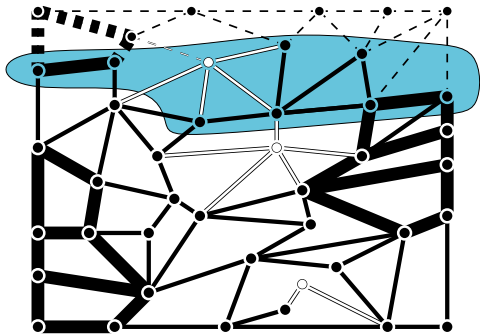


- 1 Guess the deleted vertices.
- 2 For each partial H -packing, store the size of the packing.
- 3 If there is a packing with $> \ell$ copies of H , then discard the current guess.

$\leadsto |H|^{|G|}$ packings to consider!

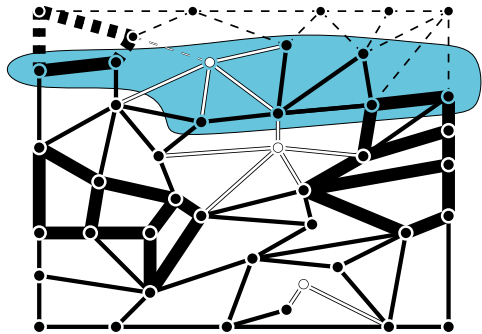
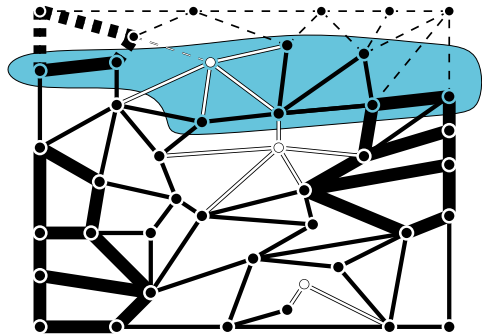


Algorithmic Idea: Improving the Running Time





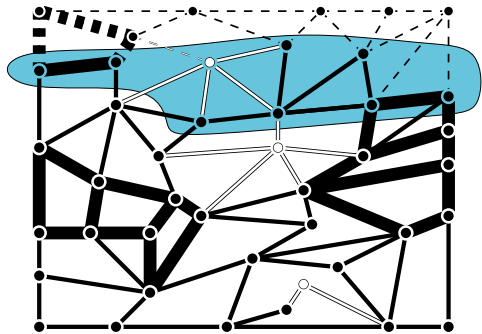
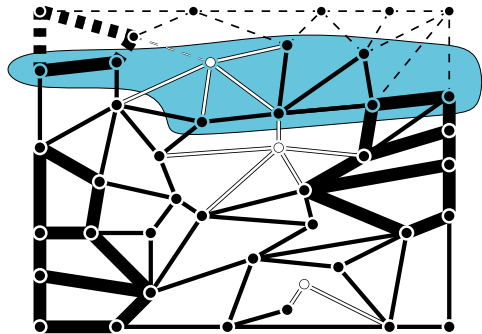
Algorithmic Idea: Improving the Running Time



1 Only the intersection with the bag matters!



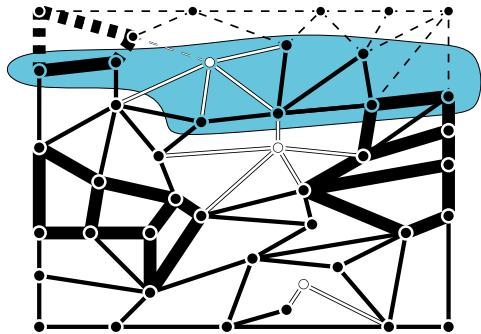
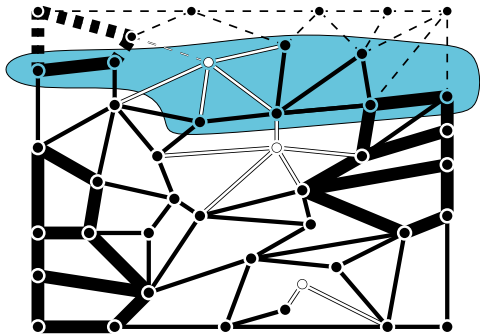
Algorithmic Idea: Improving the Running Time



- 1 Only the intersection with the bag matters!
 \rightsquigarrow Need a partition of the bag and mappings from there to H .



Algorithmic Idea: Improving the Running Time



1 Only the intersection with the bag matters!

~> Need a partition of the bag and mappings from there to H .

~> $tw^{tw} \cdot |H|^{tw}$ possible types of packings



Algorithmic Idea: Improving the Running Time

- 1 Only the intersection with the bag matters!
 - \rightsquigarrow Need a partition of the bag and mappings from there to H .
 - $\rightsquigarrow tw^{tw} \cdot |H|^{tw}$ possible types of packings



Algorithmic Idea: Improving the Running Time

- 1 Only the intersection with the bag matters!
 - \rightsquigarrow Need a partition of the bag and mappings from there to H .
 - $\rightsquigarrow tw^{tw} \cdot |H|^{tw}$ possible types of packings
- 2 For each type, the packing can have size $\in \{0, 1, 2, \dots, \ell\}$
(if it is larger, we removed the “wrong” vertices)



Algorithmic Idea: Improving the Running Time

- 1 Only the intersection with the bag matters!
 - \rightsquigarrow Need a partition of the bag and mappings from there to H .
 - $\rightsquigarrow tw^{tw} \cdot |H|^{tw}$ possible types of packings
- 2 For each type, the packing can have size $\in \{0, 1, 2, \dots, \ell\}$
(if it is larger, we removed the “wrong” vertices)
 - $\rightsquigarrow \ell^{tw^{O(tw)}}$ states for each bag



Algorithmic Idea: Improving the Running Time

- 1 Only the intersection with the bag matters!
 - \rightsquigarrow Need a partition of the bag and mappings from there to H .
 - $\rightsquigarrow tw^{tw} \cdot |H|^{tw}$ possible types of packings
- 2 For each type, the packing can have size $\in \{0, 1, 2, \dots, \ell\}$
(if it is larger, we removed the “wrong” vertices)
 - $\rightsquigarrow \ell^{tw^{\mathcal{O}(tw)}}$ states for each bag
- 3 Discard very small packings
 - \rightsquigarrow only $\mathcal{O}(tw \cdot |H|)^{tw^{\mathcal{O}(tw)}}$ states for each bag



Algorithmic Idea: Improving the Running Time

- 1 Only the intersection with the bag matters!
 - \rightsquigarrow Need a partition of the bag and mappings from there to H .
 - $\rightsquigarrow tw^{tw} \cdot |H|^{tw}$ possible types of packings
- 2 For each type, the packing can have size $\in \{0, 1, 2, \dots, \ell\}$ (if it is larger, we removed the “wrong” vertices)
 - $\rightsquigarrow \ell^{tw^{\mathcal{O}(tw)}}$ states for each bag
- 3 Discard very small packings
 - \rightsquigarrow only $\mathcal{O}(tw \cdot |H|)^{tw^{\mathcal{O}(tw)}}$ states for each bag

Theorem

For every connected graph H , H -HITPACK can be solved in time $2^{2^{\mathcal{O}(tw \log tw)}}$.



Our Contribution

Graph H	Upper Bound	Lower Bound under ETH	Completeness
Connected	$2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	no $2^{2^{\mathcal{O}(\text{tw})}}$	$\Sigma_2^P = \text{NP}^{\text{NP}}$



Our Contribution

Graph H	Upper Bound	Lower Bound under ETH	Completeness
Square	$2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	no $2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	$\Sigma_2^P = \text{NP}^{\text{NP}}$
Connected		no $2^{2^{\mathcal{O}(\text{tw})}}$	



Our Contribution

Graph H	Upper Bound	Lower Bound under ETH	Completeness
Square	$2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	no $2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	$\Sigma_2^P = \text{NP}^{\text{NP}}$
Connected		no $2^{2^{\mathcal{O}(\text{tw})}}$	
q -Clique			



Our Contribution

Graph H	Upper Bound	Lower Bound under ETH	Completeness
Square	$2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	no $2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	$\Sigma_2^P = \text{NP}^{\text{NP}}$
Connected ≥ 3 vtcs.		no $2^{2^{\mathcal{O}(\text{tw})}}$	
q -Clique			
Edge			



Our Contribution

Graph H	Upper Bound	Lower Bound under ETH	Completeness
Square	$2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	no $2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	$\Sigma_2^P = \text{NP}^{\text{NP}}$
Connected ≥ 3 vtcs.		no $2^{2^{\mathcal{O}(\text{tw})}}$	
q -Clique			
Edge	$2^{\text{poly}(\text{tw})}$	no $2^{\mathcal{O}(\text{tw})} \uparrow$	$\text{NP} \uparrow$

† Previously known



Our Contribution

Graph H	Upper Bound	Lower Bound under ETH	Completeness
Square	$2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	no $2^{2^{\mathcal{O}(\text{tw} \log \text{tw})}}$	$\Sigma_2^P = \text{NP}^{\text{NP}}$
Connected ≥ 3 vtcs.		no $2^{2^{\mathcal{O}(\text{tw})}}$	
q -Clique			
Edge	$2^{\text{poly}(\text{tw})}$	no $2^{\mathcal{O}(\text{tw})}$ †	NP^\dagger

No changes in the treewidth-DP needed!

† Previously known



The Special Case of EDGE-HITPACK

Covers Maximum Matching (Packing) and Vertex Cover (Hitting)

Standard DP: “top-down approach” for the computation

↪ DP considers all theoretically possible states



The Special Case of EDGE-HITPACK

Covers Maximum Matching (Packing) and Vertex Cover (Hitting)

Standard DP: “top-down approach” for the computation

↪ DP considers all theoretically possible states

Our DP: “bottom-up approach”

↪ DP considers only those states that actually exist



The Special Case of EDGE-HITPACK

Covers Maximum Matching (Packing) and Vertex Cover (Hitting)

Standard DP: “top-down approach” for the computation

↪ DP considers all theoretically possible states

Our DP: “bottom-up approach”

↪ DP considers only those states that actually exist

We give a *non-constructive* proof using (delta-)matroids to bound the number of states.



The Special Case of EDGE-HITPACK

Covers Maximum Matching (Packing) and Vertex Cover (Hitting)

Standard DP: “top-down approach” for the computation

↪ DP considers all theoretically possible states

Our DP: “bottom-up approach”

↪ DP considers only those states that actually exist

We give a *non-constructive* proof using (delta-)matroids to bound the number of states.

↪ Significantly faster algorithm *without any changes!*



Generalizing H -HiTPACK Further

Instead of a fixed graph H , we allow arbitrary graph objects \mathcal{X}

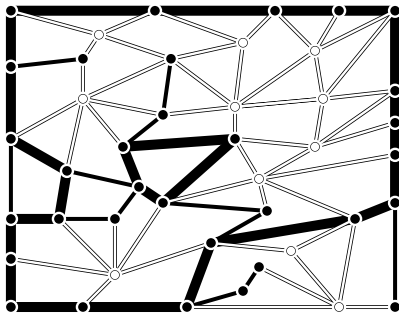


Generalizing *H*-HiTPACK Further

Instead of a fixed graph H , we allow arbitrary graph objects \mathcal{X}

\mathcal{X} = “class of all cycles”:

generalizes Feedback Vertex Set and Cycle Packing





Generalizing H -HITPACK Further

Instead of a fixed graph H , we allow arbitrary graph objects \mathcal{X}

\mathcal{X} = “class of all cycles”:

generalizes Feedback Vertex Set and Cycle Packing

Why treewidth might not always be the best parameter:

- Assume we deleted k vertices



Generalizing H -HITPACK Further

Instead of a fixed graph H , we allow arbitrary graph objects \mathcal{X}

\mathcal{X} = “class of all cycles”:

generalizes Feedback Vertex Set and Cycle Packing

Why treewidth might not always be the best parameter:

- Assume we deleted k vertices
- Erdős–Pósa: Can destroy ℓ cycles by deleting $\mathcal{O}(\ell \log \ell)$ vertices



Generalizing *H*-HITPACK Further

Instead of a fixed graph H , we allow arbitrary graph objects \mathcal{X}

\mathcal{X} = “class of all cycles”:

generalizes Feedback Vertex Set and Cycle Packing

Why treewidth might not always be the best parameter:

- Assume we deleted k vertices
- Erdős–Pósa: Can destroy ℓ cycles by deleting $\mathcal{O}(\ell \log \ell)$ vertices
- ↪ Treewidth is $\mathcal{O}(k + \ell \log \ell)$
- ↪ Algorithm with running time $2^{2^{(k+\ell) \text{poly log}(k+\ell)}}$



Generalizing H -HITPACK Further

Instead of a fixed graph H , we allow arbitrary graph objects \mathcal{X}

\mathcal{X} = “class of all cycles”:

generalizes Feedback Vertex Set and Cycle Packing

Why treewidth might not always be the best parameter:

- Assume we deleted k vertices
- Erdős–Pósa: Can destroy ℓ cycles by deleting $\mathcal{O}(\ell \log \ell)$ vertices
- \rightsquigarrow Treewidth is $\mathcal{O}(k + \ell \log \ell)$
- \rightsquigarrow Algorithm with running time $2^{2^{(k+\ell) \text{ poly log}(k+\ell)}}$

Theorem

CYCLE-HITPACK can be solved in time $2^{\text{poly}(k+\ell)}$.



Our Contribution

Graph H	Upper Bounds		LB under ETH	Completeness
Square	$2^{\mathcal{O}((k+\ell)\log(k+\ell))}$		no $2^{2^{o(\text{tw}\log\text{tw})}}$	$\Sigma_2^{\text{P}} = \text{NP}^{\text{NP}}$
Conn 3+ vtx		$2^{2^{\mathcal{O}(\text{tw}\log\text{tw})}}$	no $2^{2^{o(\text{tw})}}$	
q -Clique		$2^{2^{\mathcal{O}(\text{tw})}}$		
Edge	$3^{k+\ell}$	$2^{\text{poly}(\text{tw})}$	no $2^{o(\text{tw})}$	NP
<i>Class of all cycles</i>	$2^{\text{poly}(k+\ell)}$	$2^{2^{\mathcal{O}(\text{tw}\log\text{tw})}}$	no $2^{2^{o(\text{tw}\log\text{tw})}}$	Σ_2^{P}



Conclusion

\mathcal{X} -HITPACK generalizes \mathcal{X} -HITTING and \mathcal{X} -PACKING

- Significantly harder than base problems
- New algorithmic ideas are needed
- Some cases still allow for faster algorithms



Conclusion

\mathcal{X} -HITPACK generalizes \mathcal{X} -HITTING and \mathcal{X} -PACKING

- Significantly harder than base problems
- New algorithmic ideas are needed
- Some cases still allow for faster algorithms

Open questions:

- What about induced subgraphs or directed versions?
- Approximation results by relaxing the condition on k and ℓ ?
- Is there a non-trivial relation to Erdős–Pósa for other graph classes?



Conclusion

\mathcal{X} -HITPACK generalizes \mathcal{X} -HITTING and \mathcal{X} -PACKING

- Significantly harder than base problems
- New algorithmic ideas are needed
- Some cases still allow for faster algorithms

Open questions:

- What about induced subgraphs or directed versions?
- Approximation results by relaxing the condition on k and ℓ ?
- Is there a non-trivial relation to Erdős–Pósa for other graph classes?

Take away: Design the DPs to not waste time on impossible states.

Full version: [arXiv:2402.14927](https://arxiv.org/abs/2402.14927)

Appendix



The Vanilla Treewidth-DP

How does a typical treewidth-DP work?



The Vanilla Treewidth-DP

How does a typical treewidth-DP work?

- Identify the states of a vertex in a (partial) solution; usually a constant number of states, say c .



The Vanilla Treewidth-DP

How does a typical treewidth-DP work?

- Identify the states of a vertex in a (partial) solution; usually a constant number of states, say c .
- At each node of the tree decomposition:
Adjust the states based on the changes in the graph.



The Vanilla Treewidth-DP

How does a typical treewidth-DP work?

- Identify the states of a vertex in a (partial) solution; usually a constant number of states, say c .
- At each node of the tree decomposition:
Adjust the states based on the changes in the graph.

↪ Running time of $c^{\text{tw}^2} \cdot n^{\mathcal{O}(1)}$

(better convolution techniques frequently give $c^{\text{tw}} \cdot n^{\mathcal{O}(1)}$).



The Vanilla Treewidth-DP

How does a typical treewidth-DP work?

- Identify the states of a vertex in a (partial) solution;
usually a constant number of states, say c .
- At each node of the tree decomposition:
Adjust the states based on the changes in the graph.

↪ Running time of $c^{\text{tw}^2} \cdot n^{\mathcal{O}(1)}$

(better convolution techniques frequently give $c^{\text{tw}} \cdot n^{\mathcal{O}(1)}$).

For *H*-HITPACK the states are “deleted” and “not deleted”, so $c = 2$?!

Then why is the problem double-exponential in treewidth?



Double-Exponential Lower Bound

Reduction from SAT to *H*-HITPACK

SAT

Input: CNF-formula φ

Task: Decide if φ can be satisfied.



Double-Exponential Lower Bound

Reduction from SAT to H -HITPACK

SAT

Input: CNF-formula φ

Task:

Does there exist an assignment to the variables such that for all clauses at least one literal is true.



Double-Exponential Lower Bound

Reduction from SAT to H -HITPACK

SAT

Input: CNF-formula φ

Task:

Does there exist an assignment to the variables such that for all clauses **not all literals are false**.



Double-Exponential Lower Bound

Reduction from SAT to *H*-HITPACK

SAT

Input: CNF-formula φ

Task:

Does there exist an assignment to the variables such that for all clauses not all literals are false.

SAT

H-HITPACK

Select a variable assignment

\rightsquigarrow

Delete vertices

Select every clause (for verification)

\rightsquigarrow

Consider every packing

All literals are false

\rightsquigarrow

Packing is too large



Double-Exponential Lower Bound

Create an instance with treewidth $\mathcal{O}(\log m)$.

